eek	Date	Material	Reference
1	16-Jul-12	Ordinary Differential Equations. Examples. Linear, nonlinear.	Kreyszig 1.1
		First order ODEs. Separable. Modelling growth and decay.	1.2, 1.3
		Linear inhomogeneous. Particular integrals. Integrating factors.	1.5
2	23-Jul-12	Separable nonlinear. Spread of infection.	1.3
		Equations reducible to separable form. Bernoulli's equation.	1.
		Systems of first-order ODEs. The linear algebra connection.	4.0, 4.7
3	30-Jul-12	Matrices. Some definitions. Elementary operations, Examples.	4.0, 7.1, 7.2
		Systems of Linear Equations. Elementary row operations.	7.3
		Gaussian elimination. Examples. More on row operations.	
4	6-Aua-12	Under-determined and inconsistent equations. Rank, nullity.	7.5
	0	Determinants. Co-factors, Gaussian elim. Properties.	7.6, 7.7
		Determinants by Gaussian elimination. Inverse matrices.	7.8
5	13-Aua-12	Inverse matrices, singular matrices. Vector spaces, subspaces.	7.4, 7.9
	10 / 10 / 12	Linear combinations. Linear independence. Basis vectors, span.	7.9
		Linear Transformations. Orthogonal matrices, Similarity.	8.
7	20-Aug-12	The Matrix Eigenvalue Problem. The ODE connection.	8.1, 8.
	20-Aug-12	Eigenvalues, eigenvectors. The Cayley-Hamilton theorem.	0.1, 0.
		Diagonalization. Symmetric matrices, eigenvalue/vector properties.	8.
		Diagonalization. Symmetric matrices, eigenvalue/vector properties.	0.
	27-Aug-12	Second order ODEs. Constant coefficient. Character. Equation	2.
		Complex roots of character. Equation. Simple harmonic motion.	2.2, 2.
		Damped SHM - overdamping, critical damping, underdamping.	2.4
	3-Sep-12	Mid-Semester Break	
8	10-Sep-12	Existence of solutions. Linear independence. Wronskians.	2.
0		Reduction of order. Examples.	2.
		Inhomogeneous ODEs. Guessing a particular integral.	2.
9	17-Sep-12	Forced Oscillations. Resonance.	2.8, 2.
		Variation of parameters for inhomogeneous ODEs.	2.1
		Systems of First order ODEs. The phase plane.	4.1, 4.
10	24-Sep-12	Linear systems. Critical point. Eigenvalues.	4.
		Critical point is node, or focus, or centre, or saddle.	4.
		Nonlinear systems. Approximating by linear systems.	4.
11	1-Oct-12	Nonlinear behaviour. Limit cycles. Example: Lotka-Volterra model.	4.
		Laplace Transforms. Definition. Transforms of derivatives.	6.
		Applications to ODEs.	6.
12	8-Oct-12	Laplace Transforms of integrals. When Laplace transforms exist.	6.1, 6.
12		First and second shifting theorems. Discontinuous functions.	6.1, 6.
		ODEs with discontinuous forcing terms. Switches and circuits.	6.
13	15-0ct-12	The Dirac delta function.	6.
15	10-00t-12	Differentiation and Integration of Laplace Transforms	6.
		Inverting Transforms - Partial Fractions.	6.